

Today's Lecture



- Code, codeword, binary code
- Error detecting and correcting codes
- Hamming distance and codes
- Parity prediction
 - Odd/even parity
 - Basic parity approaches

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Error Detection through Encoding



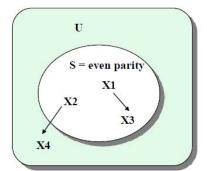
- At logic level, codes provide means of masking or detecting errors
- Formally, code is a subset S of universe U of possible vectors
- A noncode word is a vector in set U-S

X1 is a codeword <10010011> due to multiple bit error, becomes X3 = <10011100>

X2 is a codeword, becomes X4 noncode

not detectable

detectable



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Basic Idea



- Start with k-bit data word
- Add r check bits
- Total = n-bit codeword (n=k+r)
- Map 2^k data words to 2ⁿ sized codeword space
- Overhead = r/n (sometimes computed as r/k)
 - E.g., for (single-bit) parity, the overhead is 1/n

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Basic Concepts



- Code, codeword, encoding, decoding error detection code, error correcting code
- Hamming distance properties:
 - The Hamming weight of a vector x (e.g., codeword), w(x), is number of nonzero elements of x.
 - Hamming distance between two vectors x and y, d(x,y) is number of bits in which they differ.
 - Distance of a code is a minimum of Hamming distances between all pairs of code words.
 - Example: x = (1011), y = (0110)w(x) = 3, w(y) = 2, d(x, y) = 3

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Hamming Distance

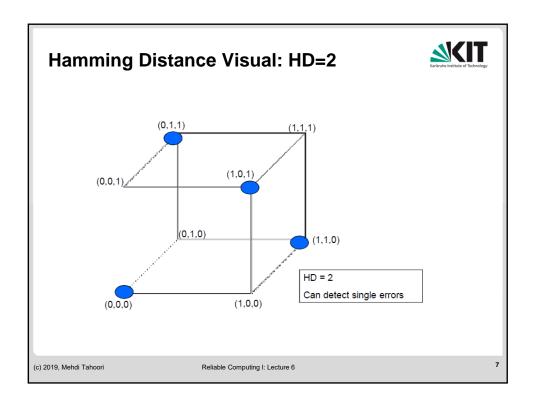


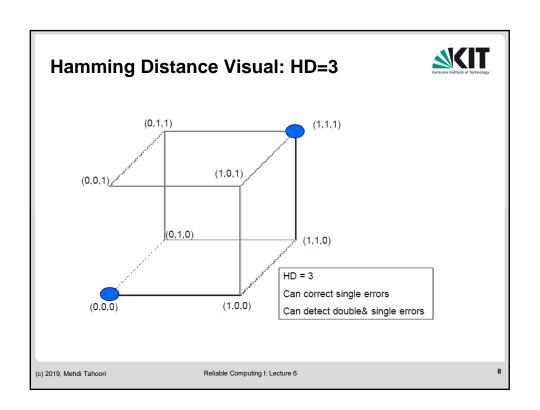
- Hamming distance (HD): number of bits in which two words differ from each other
 - E.g., 0010 and 1110 have a Hamming distance of ??
- For a group of codewords, the minimum HD between any two codewords determines the code's ability to detect and/or correct errors
 - This is a fundamental rule, not just some ad-hoc reasoning

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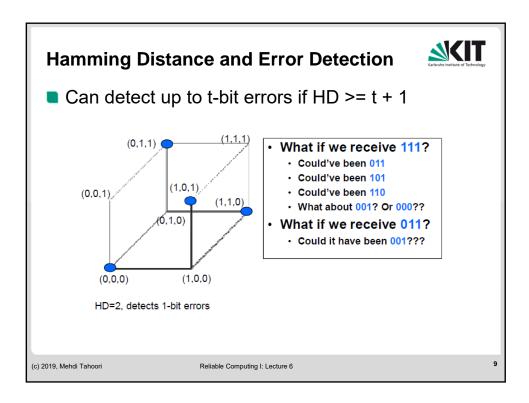
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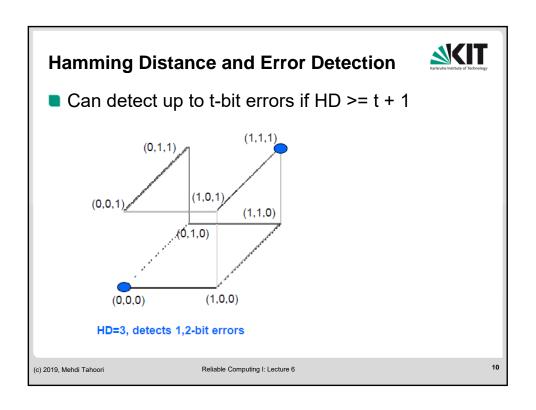




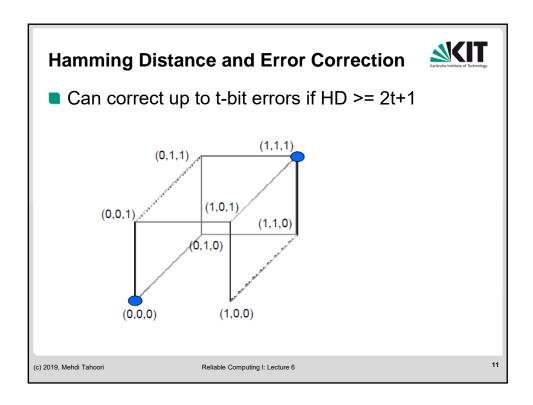


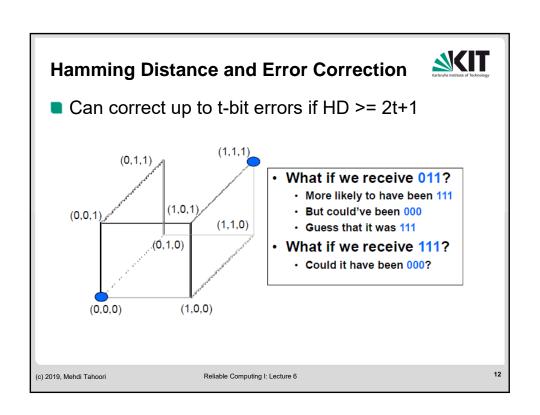














Summary: Hamming Distance Properties



- To detect all error patterns of Hamming distance ≤ d, code distance must be ≥ d+1
 - e.g., code with distance 2 can detect patterns with distance 1 (i.e., single bit errors)
- To correct all error patterns of Hamming distance ≤ c, code distance must be ≥ 2c + 1
- To correct all patterns of Hamming distance c and detect up to d additional errors ,

code distance must be ≥ 2c + d + 1

 e.g., code with distance 3 can detect and correct all single-bit errors

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Single-bit Parity

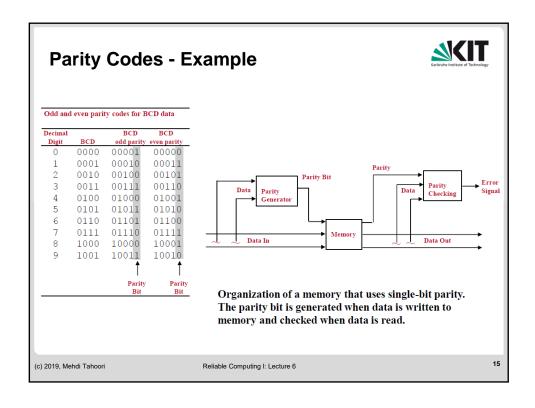


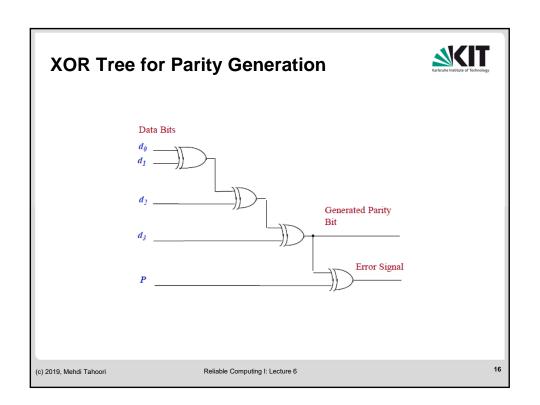
- Simplest error detection code
 - Adds one bit of redundancy to each data word
- Even (odd) parity: add bit such that total number of ones in codeword is even (odd)
 - E.g., 001010 gets a parity bit of 0 for even parity (1 for odd)
- Can detect all single-bit errors
 - Hamming distance ≥ 2
 - Could be greater than 2 if data words don't use all bit combinations
- Drawbacks:
 - Can't detect anything except single-bit errors

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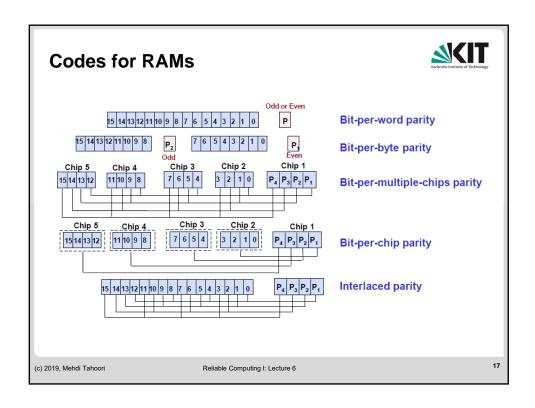
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Parity Codes for Memory - Comparison Parity Code Advantages **Disadvantages** Bit-per-word: one parity bit per data Certain errors undetected, e.g., Detects all singleword bit errors a word, including parity bit becomes all 1s, due to a failure of a bus or a set of data buffers. Bit-per-byte: each data portion (e.g., a Detects all-1s and Ineffective for multiple errors, byte) is protected by a separate parity all-0s conditions e.g., the whole-chip failure bit; the parity of one group should be even and the parity of the other group should be odd Bit-per-multiple-chips: one bit from each Detects failure of Cannot locate failure of chip is associated with a single parity bit complete chip entire chip Bit-per-chip: each parity bit is associated Detects single-bit Susceptible to whole-chip with one chip of the memory errors and failure, i.e., a single chip error identifies chip with can result in multiple bits to be erroneous bit corrupted and this may go undetected. Interlaced: similar to the bit-per-Detects errors in Parity groups are not based on multiple-chips; must ensure that no two adjacent bits physical organization of the adjacent bits are from the same parity memory group (c) 2019, Mehdi Tahoori Reliable Computing I: Lecture 6



Parity Prediction in Arithmetic Circuits



- Binary Adder
 - Two inputs: $a = (a_{n-1} ... a_0 a_c)$ and $b = (b_{n-1} ... b_0 b_c)$
 - Two operands to be added: $(a_{n-1} \dots a_0)$ and $(b_{n-1} \dots b_0)$
 - a_c and b_c are check bits of a and b respectively
 - Encoded output will be $s = (s_{n-1} ... s_0 s_c)$ where $(s_{n-1} ... s_0)$ are determined by the ordinary binary addition of $(a_{n-1} ... a_0)$ to $(b_{n-1} ... b_0)$ and s_c is the check bit for $(s_{n-1} ... s_0)$
 - Then $s_c = \sum_{i=0}^{n-1} s_i = \sum_{i=0}^{n-1} a_i \oplus \sum_{i=0}^{n-1} b_i \oplus \sum_{i=0}^{n-1} c_i$
 - Reduces to $s_c = a_c \oplus b_c \oplus \sum_{i=0}^{n-1} c_i$

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Parity Prediction in Binary Adder

An-1 Ao Ac Dan Do Dc

Binary adder

So Error

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Parity Prediction in Binary Adder

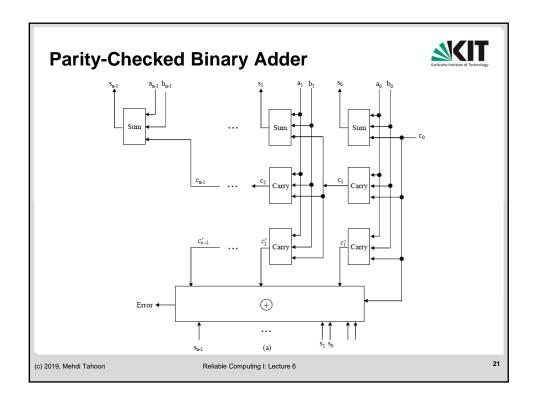
An-1 Ao Ac Dan Do Dc

Co Dan Do Dc

Error

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Binary Multiplier



$$p_0 = a_0 b_0$$

$$p_1 = a_0 b_1 \oplus a_1 b_0$$

$$p_2 = a_0 b_2 \oplus a_1 b_1 \oplus a_2 b_0 \oplus c_{1,1}$$

$$p_3 = a_0 b_3 \oplus a_1 b_2 \oplus a_2 b_1 \oplus a_3 b_0 \oplus c_{2,1} \oplus c_{1,2}$$

$$p_4 = a_1b_3 \oplus a_2b_2 \oplus a_3b_1 \oplus c_{3,1} \oplus c_{2,2} \oplus c_{1,3}$$

$$p_5 = a_2b_3 \oplus a_3b_2 \oplus c_{3,2} \oplus c_{2,3} \oplus c_{1,4}$$

$$p_6 = a_3b_3 \oplus c_{3,3} \oplus c_{2,4}$$

$$p_7 = c_{3,4}$$

■ Therefore, denoting the check bit for (p₇ ...p₀) by p_c

$$p_{c} = \sum_{i=0}^{7} p_{i}$$

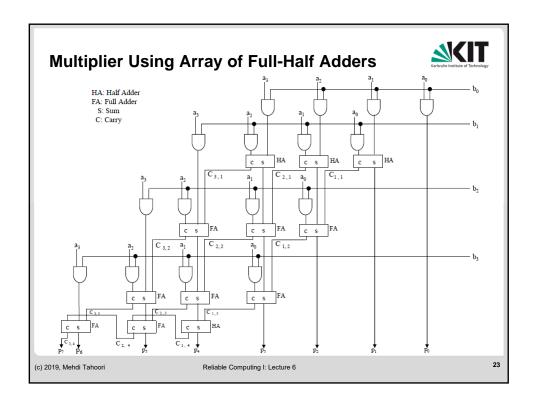
$$= (\sum_{i=0}^{3} a_{1})(\sum_{i=0}^{3} b_{1}) \oplus \sum_{i=1}^{3} \sum_{j=1}^{4} c_{i,j}$$

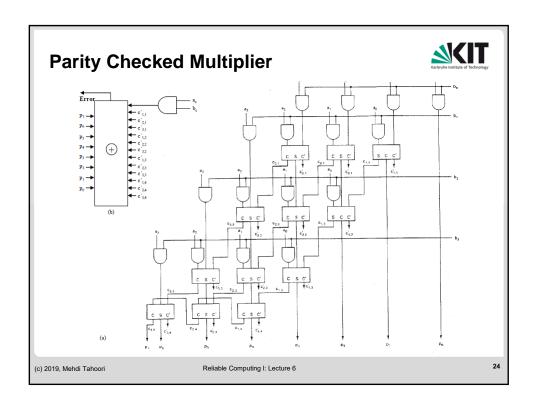
$$= a_{c}b_{c} \oplus \sum_{i=1}^{3} \sum_{j=1}^{4} c_{i,j}$$

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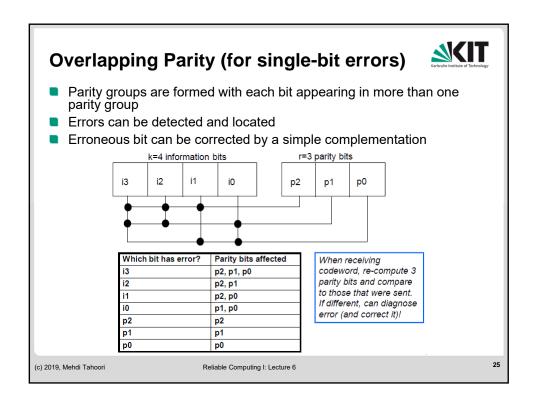
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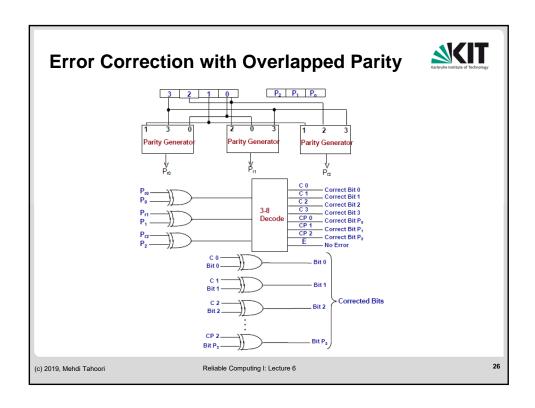














Generalized Overlapping Parity Codes



- The previous slide showed how to use overlapping parity to detect and diagnose single-bit errors
- For single-bit errors, there are k+r possible errors
 - Therefore, we need $2^r \ge k + r + 1$ to uniquely diagnose errors
- In general, can extend this scheme to detect and diagnose more than single-bit errors
 - General approach called "Hamming Codes"

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Hamming Error-Correcting Code



- Require from 10% to 40% redundancy
- Best thought of as overlapping parity
- The Hamming single-error correcting code uses c parity check bits to protect k bits of information:
 - 2^c ≥ c + k + 1
- Example:
 - suppose four information bits (d3, d2, d1, d0) and as a result three parity bits (p1, p2, p3)
 - the bits are partitioned into groups as (d3, d1, d0, p1), (d3, d2, d0, p2) and (d3, d2, d1, p3)
 - \blacksquare the grouping of bits can be determine from a list of binary numbers from 0 to 2^{k} 1.
 - each check bit is specified to set the parity, either even or odd, of its respective group

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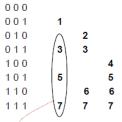
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Hamming Error-Correcting Code



Determining the bit groups (three parity bits)



Parity bits calculation

p1 = XOR of bits (3, 5, 7) p2 = XOR of bits (3, 6, 7) p3 = XOR of bits (5, 6, 7) Parity checking

c1 = XOR of bits (1,3, 5, 7) c2 = XOR of bits (2,3, 6, 7) c3 = XOR of bits (4,5, 6, 7)

Observe that each group of bits for parity checking starts with a number that is a power of 2, e.g., 1, 2, 4.

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(7,4) Hamming Code



- Class of (n,k) Hamming codes, e.g., (7,4) [r= n-k =3]
- Let i1, i2, i3, i4 be the information bits
- Let p1, p2, p4 be the check bits
- p1 = i1 xor i2 xor i4
- p2 = i1 xor i3 xor i4
- p4 = i2 xor i3 xor i4
- Let H be the Parity Check Matrix
- If \underline{C} is a codeword, then \underline{H} \underline{C} = $\underline{0}$ (mult modulo 2!)
- Else, $\underline{H} \underline{C} = \underline{S}$, where \underline{S} is the syndrome
 - Syndrome identifies where error occurred (i.e., which bit)
 - This works out like magic because of some cute math

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(7,4) Hamming Code



H =

I	p1	p2	i1	p4	i2	i3	i4
ſ	1	0	1	0	1	0	1
Γ	0	1	1	0	0	1	1
ſ	0	0	0	1	1	1	1

- Info word: 0101: p1 = 0, p2 = 1, p4 = 0
- codeword is 0100101
- Example1:
 - received error-free codeword R = 0100101
 - Compute syndrome: $\underline{S} = \underline{H} \underline{R} = \underline{0} = [0 \ 0 \ 0]$
- Example 2:
 - received R =0110101 (i.e., error in bit position 3)
 - Compute syndrome: S = H R = [1 1 0]
 - Read backwards this is 011 = 3

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Check Bits and Syndromes for Single-Bit Errors



- The original data is encoded by generating a set C_α, of parity bits.
- To check correctness, the encoding process is repeated and a set C_c, of parity bits is generated.
- If C_a and C_c agree, the information is correct.
- If C_g and C_c disagree, the information is incorrect and must be corrected.
- To aid the correction, a *syndrome* is defined:
 - The syndrome is a binary word that has 1 in each bit position in which $C_{\rm g}$ and $C_{\rm c}$ disagree; the syndrome points directly to the erroneous bit.

Erroneous bits	Check bits affected	Syndromes
d ₀	p ₁ , p ₂	110
d ₁	p ₁ , p ₃	101
d ₂	p ₂ , p ₃	011
d ₃	p ₁ , p ₂ , p ₃	111
p ₁	P ₁	100
p_2	p_2	010
D ₃	D ₃	001

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